

# t-CSA: A fast and flexible CSA Implementation

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**Abstract**—Interactive journey planning on public transport networks is a challenge. We humans cope with the journey planning challenge by intuitively searching timetables for patterns. Connection scan algorithm (CSA) is a promising algorithm to automate interactive journey planning by searching timetables for best possible journey plan. We propose t-CSA algorithm as an extension of CSA. Our contribution is two fold; Our first contribution is the inclusion of direct connection table (DCTable) in CSA to accelerate the discovery of frequent direct connections. Our second contribution is the inclusion of all known multi-modal connections between nearby stations in journey planning by using other means table (OMTable). OMTable permits customization of journey plan as per the transport facilities available to a user. Our algorithm has an average response time of 0.7ms when run on timetables of Indian public transport networks which includes both Indian railways and bus networks. We find that our algorithm makes interactive journey planning applications feasible.

## I. INTRODUCTION

In India, public transport networks are the most preferred means of transport. Ideally commuters would like to plan their journeys well in advance. This journey planning requirement from commuters gives rise to the theoretical problem of searching for a shortest path equivalent on timetables of public transport networks. Earlier, researchers in this field used graph models to represent timetables [1], [2]. Recent efforts explore more compact non-graph representations for timetables [3]–[6]. Connection scan algorithm (CSA) is one such non-graph based approach that searches timetables in linear time [7].

We propose an extended CSA which incorporates two table lookups. The first table lookup accelerates queries for direct connections. Search queries for stations on the same route also get benefit out of the proposed direct connection table (*DCTable*) lookup. The second table lookup connects nearby stations using footpath or any other known means of transport (for example, cabs); this table is named *other means table* (*OMTable*). *DCTable* reduces the average response time of the queries, where as *OMTable* adds the multi-modal private transport facilities to known public transport facilities.

The rest of the paper is organized as follows. Sec II provides summary of the literature. Sec III defines key terms used in the rest of the paper. Sec IV details basic CSA (adopted from [7]). Sec V explains the two proposed extensions to CSA and presents an improved algorithm (named t-CSA). Sec VI describes the data sets from Indian public transport networks and shows the performance of t-CSA on these data sets. Sec VII contains conclusions.

## II. RELATED WORK

Algorithm researchers have made noteworthy contributions to improve real-time transit query performance on public transport networks. Initial research efforts focused on adoption of best algorithms developed for routing on road networks to the public transport networks [2], [8]. Over the years, researchers have discovered significant differences between the two problems, namely routing on road networks *vs* best itinerary on public transport networks. Bast et al. provides an overview of these differences and a summary of query speed-up techniques for public transport (timetable) networks [9]. Bast et al. also provide a detailed survey of algorithms used on road networks and public transport networks [2].

Over the years, researchers converged onto time-expanded (TE) graphs and time-dependent (TD) graphs as two appropriate graph-based models for representing public transport networks (also known as timetable networks) [1], [10]. In TE graphs, each arrival and departure event is represented as a vertex and the travel time as a weighted edge [11]. TE graph model was originally proposed by Schultz et al. and then extended by Müller-Hannemann et al. [11], [12]. The widely used General Transit Feed Specification (GTFS) is a TE graph based representation of timetable [13].

Delling et al. contract the arrival and departure nodes of TE graphs completely [14]. They also parameterize the contraction of transfer nodes. Bast et al. modify the edges of TE graph model to represent periodic trips. The resulting transfer patterns algorithm requires costly preprocessing but provides query responses in a few milliseconds [15].

Orda et al. propose time dependent (TD) graph model and give shortest path algorithm [16], [17]. Brodal et al. use TD graphs for executing fast itinerary search queries [18]. In basic TD graphs model, vertices represent stations and edges represent trips, routes. In expanded TD graph model (TD+), even routes have station-specific vertices; such expanded TD models have been referred to as train route graphs [1]. Geisberger et al. proposes station graph model which is an application of contraction hierarchies preprocessing technique to TD graph [19].

Connection Scan Algorithm (CSA), RAPTOR, GBR, and FBS are the non-graph based approaches to transit routing [3]–[6]. CSA represents timetables using connections; Strasser et al. shows equivalence between running CSA and computing shortest path queries on TE-graphs. *RAPTOR*, short for Round-

based Public Transit Routing, utilizes trips and routes for itinerary computation and is equivalent to queries on TD-graphs [4], [6]. *GBR*, short for guidebook routing, utilizes network flow-based approach to generate time independent itineraries for a given timetable [5]. *FBS*, short for frequency-based search, shows a way to extract and represent frequent-trips from timetables [4].

CSA uses connection as a fundamental unit for decomposing timetables and searching these decomposed timetables. Such a clean representation allows quick update of searchable timetables for possible delays, cancellations and special trips on busy occasions. An update of timetables only requires changing effected connections of CSA. CSA has been proven to be faster than RAPTOR, TE and TD-graph based algorithms for one-to-one queries [2], [3]. Only transfer patterns is faster than CSA, but transfer patterns technique requires costly preprocessing [2], [15].

Our work adopts techniques outlined in CSA, and transfer patterns papers [3], [15]. We propose an extension to CSA using DCTable. DCTable approach is similar to direct connections of transfer patterns [15]. Such a direct connection table approach has given rise to transit node routing (TNR) algorithm – the best performing algorithm for road networks in terms of query response time [20]. The OMTable extends footpath table of CSA to incorporate frequent trips. We include private transport networks in OMTable; Consequently, connection array gets augmented with private transport networks. Similar approaches such as GBR and FBS affirm the need to concisely represent frequent connections of a timetable. Our other means table (OMTable) can incorporate private transit facilities available to users, thus bridging the gap between public and private transport networks.

### III. PROBLEM STATEMENT

#### Definitions

Public transport networks contain a set of stations ( $S$ ) where vehicles stop to pickup or drop-off passengers. These vehicles cover a well-defined sequence of stations; The arrival and departure times of a vehicle at a station is well known. One instance of a vehicle starts at one station, goes through a well-defined sequence of stations and stops at a station. The vehicle arrives at each station at arrival time ( $t_{arr}$ ) and departs at the departure time ( $t_{dep}$ ). The sequence of stations including the first and last stations along with their respective arrival and departure times is defined as a *trip*. A mathematical formulation of a trip is shown in Figure 1.

The arrival and departure times at a station  $S_i$  are indicated as  $(t_{arr_i}, t_{dep_i})$ . The arrival time at the starting station and the departure time at the ending station are undefined. The time difference  $(t_{dep_i} - t_{arr_i})$  is the waiting time at  $i^{th}$ -station [3].

In public transport networks vehicles go on a trip, return to the starting station (through another trip) and repeat such a loop many times during one time period (a day / a week / a fortnight); we call such trips as *loop trips*. In such cases, we consider the onward and return trips as two distinct trips.

	$S_1$	$S_2$	...	$S_n$	VehID
$t_1$	$(-, t_{dep_1})$	$(t_{arr_2}, t_{dep_2})$	...	$(t_{arr_n}, -)$	$ID_1$
	$\underbrace{\hspace{10em}}_{\text{Connection } (C)}$				
$t_2$	$(t_{arr_1}, -)$	$(t_{arr_2}, t_{dep_2})$	...	$(-, t_{dep_n})$	$ID_1$

Fig. 1. Sample trips  $t_1$  and  $t_2$  undertaken by vehicle identified as  $ID_1$ . The trips  $t_1$  and  $t_2$  together form a loop trip.

An interesting variation on loop trips is a *circular trip* where a vehicle starts at station  $S_1$ , goes through a series of stations  $S_i$  and terminates the trip at  $S_1$  again. For circular trips, the following timing constraint holds.

$$\forall i, j \in [2, n] \text{ and } j > i, \\ t_{dep_1} < t_{arr_i} < t_{dep_i} < t_{arr_j} < t_{dep_j} < t_{arr_1}$$

Two typical events can happen in public transport system. One, a vehicle makes multiple loop trips covering same stations with each trip having different arrival and departure times; Two, between busy stations, multiple vehicles cover the same sequence of stations with each vehicle undertaking multiple trips. *Route* ( $r$ ) is a set of all trips that cover the exact same sequence of stations and satisfy first-in-first-out (FIFO) property [3].

$$r = \{t_1, t_2, \dots, t_m\}$$

FIFO property guarantees strict time-ordering of all trips belonging to a route. A common sense way of saying this is, "on a route, waiting never pays off".

By definition, all routes of a public transport system are mutually disjoint, i.e., no two routes contain a common trip. Since trips belonging to different routes can have overlapping stations, routes may have a few common stations.

We can define *timetable* for a public transport system as a tuple  $(\pi, S, T, R, F)$ .  $\pi$  denotes time period of a timetable; often this time period is a day or a week.  $S$  is the set of all stations,  $T$  is the set of all trips,  $R$  is the set of all routes and  $F$  is a footpath table containing walking times between nearby stations [6].

A *connection* is a fundamental unit of timetable [7]. A connection is defined as

$$C = (S_{dep}, t_{dep}, S_{arr}, t_{arr}, tr) \\ \text{where,} \\ tr = \text{unique trip identifier} \\ \text{other variables as defined before}$$

We can rephrase trip as a sequence of connections. For a trip covering  $n$  stations, we will have  $(n-1)$  connections.

$$t = C_1 C_2 \dots C_{n-1} \\ \text{where } C_i = (S_i, t_{dep_i}, S_{i+1}, t_{arr_{(i+1)}}), tr)$$

#### Connection Array

In the previous section, we have shown a way to transform timetables into elementary connections. We know that each connection has a start time. Based on the start times, we can

**Query:**  $S_1@00 : 10 \rightarrow S_5$

**Itinerary:**

- 1) Wait for 5 minutes at  $S_1$ .
- 2) Take  $t_2 = C_4C_5C_6$  from  $S_1$  to  $S_4$  and reach  $S_4$  by 02 : 10.
- 3) Wait for 30 minutes at  $S_4$ . (transfer from  $t_2$  to  $t_3$ )
- 4) Take  $C_8$  (part of  $t_3$ ) and reach  $S_5$  at 03 : 15.

Fig. 2. A sample query and the generated itinerary.

sort the connections in ascending order and place the resulting connection sequence in an array. This array is called *connection array*. In a connection array, let  $i$  and  $j$  be the positions of two connections, then  $t_{dep}(C_i) \leq t_{dep}(C_j) \forall i < j$ .

Timetables of public transport systems tend to be periodic; Often, the time period is a day, a week or a fortnight. We can easily incorporate the periodicity by making the following adjustments to the connection array.

- 1) Connection array becomes a circular list. i.e., after last connection in the array, we can pursue the first connection in the connection array to determine the travel itinerary.
- 2) Arrival and departure times of each connection need to be adjusted based on the number of passes through the connection array.

$$t'_{arr} = i \times 1440 + t_{arr}$$

$$t'_{dep} = i \times 1440 + t_{dep}$$

where,  $i = 0, 1, 2, \dots, k$  is the number of passes made through the connection array. For practical purposes, we can limit  $k$  to 3 days even for country-wide timetables.

*Feasible Itinerary*

An itinerary (I) is made up of a sequence of connections,  $I = C_1C_2 \dots C_h$  with consecutive connections satisfying the condition  $S_{arr}(C_i)$  is equal to  $S_{dep}(C_{i+1})$ . Each of the consecutive connections of an itinerary may belong to the same trip. If two consecutive connections are not part of the same trip, a *transfer* is required at the corresponding station.

A representative query from user and the itinerary generated using connection array are shown in Figure 2. The itinerary shown in Figure 2 is feasible because the commuter can catch  $C_8$  after  $C_6$ . If  $C_8$  were to depart anytime before 02 : 10, the itinerary would have become in-feasible.

*Transfer Times*

In simple connection model, *transfer time* – the time required for alighting a connection of one trip and boarding connection of another trip (*trip transfer*) – has been assumed to be zero. But in reality, transfer times are non-zero. The transfer time is often dependent on connections, station at which transfer occurs and the time of day. The transfer time

is zero for a commuter not undertaking the trip transfer at a station. We can represent transfer time as

$$t_{tr}(C_i, C_j) = 0 \quad \text{if } C_i, C_j \in \text{same trip} \\ = f(C_i, C_j) \text{ else}$$

We can approximate  $f(C_i, C_j)$  as

$$f_1(C_i, C_j) \approx f_2(S_{arr}(C_i), t) \approx f_3(S_{arr}(C_i))$$

where,  $f_1 : C_i \times C_j \rightarrow T, f_2 : S \times T \rightarrow T, f_3 : S \rightarrow T$

Function  $f_3$  is sufficient to model transfer times in most practical scenarios. In the rest of the paper, we will use function  $f_3$  to model transfer times.

With non-zero transfer times, a transfer  $C_i$  to  $C_j$  is feasible if only if

$$S_{arr}(C_i) = S_{dep}(C_j) \text{ and} \\ t_{dep}(C_j) \geq t_{arr}(C_i) + t_{tr}(C_i, C_j) \\ \approx t_{arr}(C_i) + t_{tr}(S_{arr}(C_i))$$

IV. CONNECTION SCAN ALGORITHM (CSA)

In this section, we give an outline of algorithm that operate on a connection array to produce travel itinerary. This algorithm have been called a connection scan algorithm (CSA) [7]. A basic version of CSA is given in Algorithm 1. Algorithm 1 requires connection array ( $CA$ ), starting station ( $S_1$ ), start time ( $t_s$ ), ending station ( $S_2$ ), and station array ( $SA$ ) as inputs. If possible, the Algorithm 1 produces a feasible itinerary ( $I$ ). Algorithms 1 and 2 use a few temporary variables during their operation. These temporary variables are as follows:  $IC$  is an array to hold incoming connections for each station;  $d$  is an array to hold the earliest arrival time for each station;  $C_i$  is a temporary connection variable to hold the connection under consideration.

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**Algorithm 1** Connection Scan Algorithm (CSA)

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**Input:**  $CA, S_1, t_s, S_2, SA$

**Output:**  $I$

- 1: ▷ Temporary variables:  $IC, d, C_i$
  - 2: **for all**  $s_i \in SA$  **do**
  - 3:      $IC[s_i] \leftarrow \text{null}$
  - 4:      $d[s_i] \leftarrow \infty$
  - 5: **end for**
  - 6: ▷ Compute itinerary
  - 7: **for all**  $C_i \in CA$  **do**
  - 8:     **if**  $t_{dep}(C_i) > d[S_{dep}(C_i)]$  **and**  
         $t_{arr}(C_i) < d[S_{arr}(C_i)]$  **then**
  - 9:          $d[S_{arr}(C_i)] \leftarrow t_{arr}(C_i)$
  - 10:          $IC[S_{arr}(C_i)] \leftarrow C_i$
  - 11:     **end if**
  - 12: **end for**
  - 13:  $I \leftarrow \text{ITINERARY}(IC)$
  - 14: **return**  $I$
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Algorithm 1 operates as follows. The arrays  $IC$  and  $d$  are initialized. The for loop given in the lines 7–12 iterates through each connection and tries to settle the arrival station of a connection. If the relaxation function ( $d$ ) of arrival station

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**Algorithm 2** Fetch itinerary through backtracking (ITINERARY)

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**Input:**  $IC$

**Output:**  $I$

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1:                                     ▷ Temporary variable:  $C_i$ 
2:  $I \leftarrow null$ 
3:  $C_i \leftarrow IC[S_2]$ 
4: while  $C_i$  do                               ▷ valid connection
5:   I.PREPEND(C)                               ▷ add at the beginning
6:    $C_i \leftarrow IC[S_{dep}(C_i)]$ 
7: end while
8: return  $I$ 

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can be modified, the corresponding entries are updated in the incoming connections array ( $IC$ ). After processing all the connections, Algorithm 1 uses Algorithm 2 to extract an optimal itinerary from  $IC$  array.

## V. EXTENSIONS TO CSA

### Fast Lookups

CSA gives fast query response (<2 ms) even on country-wide multi-mode timetables. We reduce the queries times even further by storing answers to queries of direct connections that can be answered directly from timetable. Such direct connections are the norm in long-distance bus networks. For these scenarios, direct lookup is optimal.

We copy all such direct connections cases from timetables and place them in  $DCTable$ , short for direct connections table. Entries in the  $DCTable$  are stored as as connection tuples. Any incoming query is first checked against a match in  $DCTable$ ; Upon a match in the  $DCTable$ , all possible direct connections/itineraries between two stations specified in the query are returned. If an answer is not found, then CSA is run.  $DCTable$ 's role can be augmented as a cache for popular queries.

### Footpaths and Other Means

In case two public transport stations are nearby, the passengers can alight a connection at one station, walk to the nearby station on footpath and board a new connection. For all nearby stations of the public transport network, we can maintain a table of walk times. A sample set of entries are shown in Table I.  $f_{start}$  denotes starting station,  $f_{end}$  denotes ending station and  $t_w$  indicates walk time.

TABLE I  
FOOTPATHS TABLE.

$f_{start}$	$f_{end}$	$t_w$
$S_i$	$S_j$	$t_{w1}$
$S_j$	$S_k$	$t_{w2}$
$S_i$	$S_k$	$t_{w3} \leq t_{w1} + t_{w2}$

All entries are transitively closed which enables a direct lookup of all possible walks between nearby stations. If the entries were not transitively closed, we would have been forced

to run shortest path algorithm on the table for each query, an expensive proposition.

No single public transport network provides best any-station to any-station connectivity at all times. Our footpath table is a more effective way of reaching nearby stations. We can segregate all known means of transport into public transport system with timetable and everything else (*other means*). Popular other means could be footpaths, autos, taxis, car pools or a helpful drop by a friend. The transport by other means can be summarized into a table named *other means table* (OMTable). Entries in OMTable will be a tuple of the form  $(S_i, S_j, \text{travel time, details})$ . The format of OMTable is given in Table II.

TABLE II  
OTHER MEANS TABLE.

$S_{start}$	$S_{end}$	$t_{omt}$	Details
$S_i$	$S_j$	10 min	walk
$S_i$	$S_k$	30 min	cab

Connection array is a very efficient representation for aperiodic connections. Most timetables have high-frequency trips between popular stations, say a bus every 5 minutes between  $S_i$  and  $S_j$ . One such timetable entry leads to 288 connections in the connection array. Such routes have been called as guidebook routes or transfer patterns [4], [5], [15]. We can efficiently represent such cases in OMTable.

### $t$ -CSA Algorithm

CSA outlined in Algorithm 1 assumes the zero transfer times. It also assumes that an itinerary can be found on or before we reach the end of connection array ( $CA$ ). End of  $CA$  is also the stop condition for the loop given in lines 7 – 12 of Algorithm 1. We can redesign the basic CSA to overcome these three limitations.

An enhanced version of CSA (named,  $t$ -CSA) that incorporates modifications is shown in Algorithm 3. Algorithm 3 builds on Algorithm 1. Over and above the inputs required by Algorithm 1, Algorithm 3 requires four additional inputs. These additional inputs are: the maximum number of travel days ( $n$ ), station transfer times array ( $TT$ ), direct connections table ( $DCTable$ ) and other means table ( $OMTable$ ).  $C_j$ ,  $C_{last}$ ,  $itr$ ,  $n_{ca}$ ,  $t_{dep}$ ,  $t_{arr}$  and  $settled$  are the newly introduced temporary variables.  $C_j$  denotes the first connection in the connection array with a starting time  $t_{dep}(C_j) > t_s$ .  $C_{last}$  holds the last connection in the connection scan array.  $itr$  specifies the number of times the connection array needs to be scanned for creating a feasible itinerary.  $n_{ca}$ ,  $t_{arr}$  and  $t_{dep}$  are the temporary variables used to enhance readability.  $settled$  indicates a change in earliest arrival estimate at a station.

The first major addition to Algorithm 3 over Algorithm 1 is the  $DCTable$  code given in lines 2 – 5.  $DCTable$  is consulted first; only in case the query fails on  $DCTable$ , will the CSA be run. The function call on line 12 returns  $C_j$ . In abstract terms, CONNSEARCH performs a binary search on connection array to find the connection  $C_j$  that satisfies the condition.

$$\min t_{dep}(C_j) - t_s$$

With Constraints:

$$t_{dep}(C_j) - t_s > 0$$

$$C_j \in CA$$

The code block in lines 13 – 46 iterates through connection array required number of times, examines all eligible connections and tries to settle stations whenever relaxation is possible. The code in lines 20 – 24 considers realistic station transfer times. Another feature addition is *settling* the nearby stations of a recently *settled* station by using the entries of other means table (*OMTable*). The corresponding code is in lines 33 – 41 of Algorithm 3. Early termination condition on line 42 helps us discard all connections whose departure times are greater than the current estimate of the earliest arrival time at the destination station.

## VI. EXPERIMENTS

### Data Sets

We utilize transport data available from Indian public transport networks. The characteristics of the networks selected are summarized in Figure 3. The #Stations and #Connections columns indicate the number of stations and connections respectively. The train data has been obtained from Indian Railways timetable [21]. This railway timetable network is the largest Indian public transport network utilized by us. The flight data has been generated from the domestic flight schedules released by Directorate General of Civil Aviation (DGCA), India [22]. The bus data has been obtained from numerous public and private bus transport operators (for one such example, namely GSRTC, see [23]).

### Query Times

Algorithms 1, 2 and 3 have been coded in Python2.7 programming language and tested on a commodity laptop. The laptop has 2-core 64-bit Intel i5-2430M processor with 256KB of L2 cache and 3MB of L3 cache; the operating system is 64-bit Ubuntu. We run queries on complete Indian network (has 2264 stations and 59555 connections). We randomly generate 1000 queries with randomly chosen source, destination pairs and a random start time. Our Python2.7 implementation of Algorithm 1 gives an average query response time 0.5ms. Algorithm 3 gives an average query response time of 0.7ms. The direct connection queries on *DCTable* execute very fast (worst case time:  $1\mu s$ ; average time:  $0.5\mu s$ ). These numbers compare favorably with average response time of 1.8ms for London metropolitan data reported in [3].

## VII. CONCLUSIONS

We use connection as a building block to model timetables of public transport networks. We propose t-CSA which adds direct connection table (*DCTable*) and other means table (*OMTable*) to connection scan algorithm. *DCTable* stores itinerary details of stations that are directly connected through a trip. *OMTable* stores details of alternative (footpath and miscellaneous modes of transport) connections between

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### Algorithm 3 An enhanced CSA (t-CSA)

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**Input:**  $CA, S_1, t_s, S_2, SA, n, TT, DCTable, OMTable$   
**Output:**  $I$

- 1:  $\triangleright$  Temporary variables:  $IC, d, C_i, C_j, C_{last}, itr, n_{ca}, t_{dep}, t_{arr}, settled, C_{temp}$
- 2:  $\triangleright$  try direct connections first
- 3: **if**  $I \leftarrow \text{SEARCHDCT}(DCTable, S_1, t_s, S_2)$  **then**
- 4:     **return**  $I$
- 5: **end if**
- 6:      $\triangleright$  Compute number of iterations
- 7:  $C_{last} \leftarrow CA[CA.length - 1]$
- 8:  $n_{ca} \leftarrow t_{dep}(C_{last}) \bmod 1440$
- 9:  $itr \leftarrow n \bmod n_{ca}$
- 10: Initialize  $IC$  and  $d$  as per lines 2-5 of Algorithm-1
- 11:      $\triangleright$  Pick first connection with  $t_{dep}(C) > t_s$
- 12:  $C_j \leftarrow \text{CONNSEARCH}(CA, t_s)$
- 13: **search:**
- 14: **for all**  $day \leftarrow 1, 2, \dots, (itr + 1)$  **do**
- 15:     **if**  $day == 2$  **then**
- 16:          $C_j \leftarrow C_0$
- 17:     **end if**
- 18:     **for all**  $C_i \in CA \ni C_i \geq C_j$  **do**
- 19:          $settled \leftarrow false$
- 20:         **if**  $tr(C_i) == tr(IC[S_{dep}(C_i)])$  **then**
- 21:              $t_{tr} \leftarrow 0$
- 22:         **else**
- 23:              $t_{tr} \leftarrow TT[S_{dep}(C_i)]$
- 24:         **end if**
- 25:          $t_{dep} \leftarrow t_{dep}(C_i) + day \times 1440$
- 26:          $t_{arr} \leftarrow t_{arr}(C_i) + day \times 1440$
- 27:         **if**  $t_{dep} > d[S_{dep}(C_i)] + t_{tr}$  **and**  
 $t_{arr} < d[S_{arr}(C_i)]$  **then**
- 28:              $settled \leftarrow true$
- 29:              $d[S_{arr}(C_i)] \leftarrow t_{arr}(C_i)$
- 30:              $IC[S_{arr}(C_i)] \leftarrow C_i$
- 31:         **end if**
- 32:          $\triangleright$  use *OMTable* to settle nearby stations
- 33:         **if**  $settled$  **then**
- 34:             **for all**  $S_{arr}(C_i), S_j \in OMTable$  **do**
- 35:                 **if**  $d[S_j] > d[S_{arr}(C_i)] +$   
 $t_{omt}[S_{arr}(C_i), S_j]$  **then**
- 36:                      $d[S_j] \leftarrow d[S_{arr}(C_i)] +$   
 $t_{omt}[S_{arr}(C_i), S_j]$
- 37:                      $C_{temp} \leftarrow (S_{arr}(C_i), t_{arr}(C_i), S_j,$   
 $t_{arr}(C_i) + t_{omt}[S_{arr}(C_i), S_j], om)$
- 38:                      $IC[S_j] \leftarrow C_{temp}$
- 39:             **end if**
- 40:         **end for**
- 41:     **end if**
- 42:     **if**  $t_{dep} > d[S_2]$  **then**
- 43:         **break** **search**
- 44:     **end if**
- 45: **end for**
- 46: **end for**
- 47:  $I \leftarrow \text{ITINERARY}(IC)$
- 48: **return**  $I$

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Name of Network	Mode of Transport	#Stations	#Connections	CA size
Indian Railways (IR)	train	2136	44876	0.36 MB
Indian Flights (IFlights)	flight	80	2501	0.02 MB
Long Distance Buses (LDB)	bus	147	12219	0.1 MB
Complete Network (India)	multi-mode	2264	59555	0.52 MB

Fig. 3. Summary of timetables obtained from Indian public transport networks.

nearby stations. We find that t-CSA extends the capabilities of CSA significantly.

We also demonstrate the implementation of extended CSA on timetables of Indian public transport networks. Our t-CSA eliminates the need to run CSA on direct connection queries. Since direct connection queries are the bulk of queries on timetables, t-CSA significantly accelerates interactive journey planner applications.

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